

[Back to Previous Page](#)**Results Key:****JNL** = Journal or Magazine **CNF** = Conference **STD** = Standard**1 SOI-fabrication of scanning mirror for laser display**

Jin-Ho Lee; Young-Chul Ko; Byoung-So Choi; Jong-Min Kim; Duk Young Jeon;
Optical MEMS, 2002. Conference Digest. 2002 IEEE/LEOS International Conference
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Pages:153 - 154

IEEE CNF**2 Employing electrical field sensing for detecting static thumb position using
the Finger-Joint Gesture Keypad input paradigm**

Goldstein, M.; Baez, O.; Danielsson, P.;
Wearable Computers, 2000. The Fourth International Symposium on , 16-17 Oct. 2000
Pages:173 - 174

IEEE CNF**3 Vibrotactile sensor generating impulsive signals for distinguishing only
slipping states**

Yamada, Y.; Morita, H.; Umetani, Y.;
Intelligent Robots and Systems, 1999. IROS '99. Proceedings. 1999 IEEE/RSJ
International Conference on , Volume: 2 , 17-21 Oct. 1999
Pages:844 - 850 vol.2

IEEE CNF**4 A microfabricated electrostatic haptic display for persons with visual
impairments**

Hui Tang; Beebe, D.J.;
Rehabilitation Engineering, IEEE Transactions on [see also IEEE Trans. on Neural
Systems and Rehabilitation] , Volume: 6 , Issue: 3 , Sept. 1998
Pages:241 - 248

IEEE JNL**5 Development of artificial finger skin to detect incipient slip for realization of
static friction sensation**

Fujimoto, I.; Yamada, Y.; Morizono, T.; Umetani, Y.; Maeno, T.;
Multisensor Fusion and Integration for Intelligent Systems, MFI2003. Proceedings of
IEEE International Conference on , 30 July-1 Aug. 2003
Pages:15 - 20

IEEE CNF**6 Static friction coefficient determination by force sensing and its application**

Bayrleithner, R.; Komoriya, K.;
Intelligent Robots and Systems '94. 'Advanced Robotic Systems and the Real World',

IROS '94. Proceedings of the IEEE/RSJ/GI International Conference on , Volume: 3 , 12-
16 Sept. 1994
Pages:1639 - 1646 vol.3

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